

Abstract

This study is to control the car through the motor forward and backward and turn, and the use of sg-90 and mg-90 control arm stretching and claw opening and closing. In the control section, the phone uses the app inventor to connect the phone through the Bluetooth transmission control code. Arduino is the use of HC-06 Bluetooth to connect the phone to receive the control code, when the Arduino Bluetooth control code will receive the implementation of the relative program, so that the car can follow our instructions to move and gripping items.